

Computational Logic

Extraction of Answers

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Introduction

From ATP to extraction of answers

- the techniques for automated theorem proving can be also used for designing systems for extracting answers and solving problems
- we focus on resolution

The idea

- the facts which are needed to find an answer or solve a problem can be seen as axioms or premises
- the question or the problem can be seen as a theorem to be proven

Kinds of questions (and answers)

(A) yes/no questions

- is Luís in Madrid? Yes, Luís is in Madrid

(B) questions like *where is*, *who is*, *under which conditions*, ...

- where is Luís? Luís is in Madrid

(C) questions whose answer is a sequence of actions

- what do I have to do? Go to Madrid and take the train

(D) questions whose answer includes verifying some conditions

- what do I have to do? If there are still seats, go to Madrid and take the train, otherwise take the bus

Type A

The correspondence

Since the answer can only be *yes* or *no*, it can be obtained by solving the deduction problem

given A_1, \dots, A_n , is P certainly true? \rightsquigarrow $[A_1, \dots, A_n] \vdash P$

Example

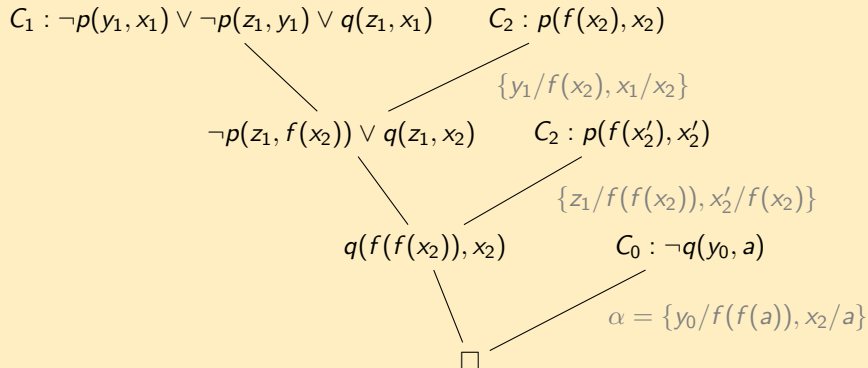
if one is in Madrid, then (s)he's not in Lugo $\neg p(x, \text{Madrid}) \vee \neg p(x, \text{Lugo})$
Luís is in Madrid $p(\text{Luis}, \text{Madrid})$
is Luís in Lugo? $\neg p(\text{Luis}, \text{Lugo})$

- it's not possible to derive \square from this, so that we should not answer that Luís is in Lugo
- if the conclusion cannot be proven, then we should try to prove its negation
- if neither can be proven, then the answer should be *not enough information*

Type B

The grandfather

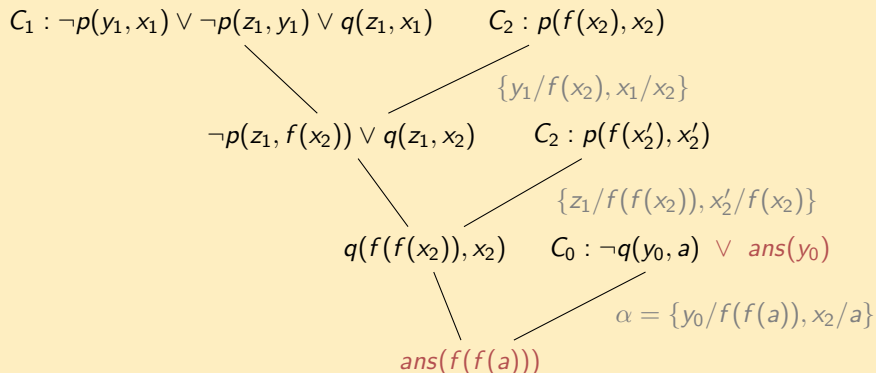
if y is x 's father and z is y 's father, then z is x 's grandfather C_1
everyone has a father C_2
who is a 's father? C_0



Type B

The grandfather

if y is x 's father and z is y 's father, then z is x 's grandfather C_1
everyone has a father C_2
who is a 's father? C_0

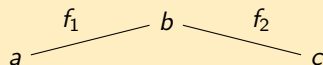


The task

Find a sequence of actions for reaching a goal

- every *object* is supposed to be in a given *state*
- to reach the goal, the state has to be changed to the desired state
- ATP can be used for finding the actions which can produce the change

Example



- $p(x, y, z)$: x is in state z at y
- $f_1(x, a, b, z)$: final state obtained by moving from a to b the object x which is in state z
- $f_2(x, b, c, z)$: final state obtained by moving from b to c the object x which is in state z

how can d go from a to c ?

d is initially in a , with state s_1

$$C_0: \neg p(d, c, z) \vee \text{ans}(z)$$

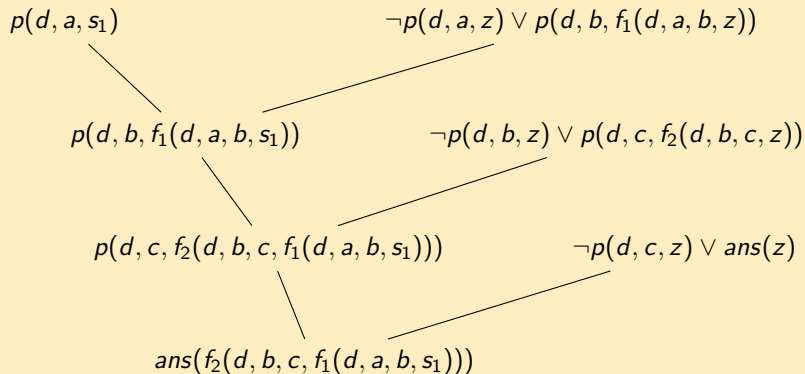
$$C_1: p(d, a, s_1)$$

$$C_2: \neg p(d, a, z) \vee p(d, b, f_1(d, a, b, z))$$

$$C_3: \neg p(d, b, z) \vee p(d, c, f_2(d, b, c, z))$$

Type C

Example



- f_1 takes d from a to b
- f_2 takes d from b to c

The monkey and the banana

Predicates

- $p(x, y, z, s)$: in the state s , the monkey is at x , the banana is at y and the chair is at z
- $r(s)$: in the state s , the monkey can reach the banana

Functions

- $walks(y, z, s)$: the state reached when the monkey walks from y to z starting in the state s
- $takes(y, z, s)$: the state reached when the monkey, starting in the state s , walks from y to z taking the chair with itself
- $climbs(s)$: the state reached when the monkey, starting in the state s , climbs the chair

The monkey and the banana

Axioms

- $p(a, b, c, s_1)$
- $\neg p(x, y, z, s) \vee p(z, y, z, \text{walks}(x, z, s))$
- $\neg p(x, y, x, s) \vee p(y, y, y, \text{takes}(x, y, s))$
- $\neg p(b, b, b, s) \vee r(\text{climbs}(s))$

Question

- $\neg r(s) \vee \text{ans}(s)$

Do these axioms allow the monkey to do whatever it wants?

Type D

The idea

- the task is to find a sequence of actions which, *under certain conditions*, can take to the goal
- it makes sense when the given information does not allow a definite decision

How it works

- every *object* is supposed to be in a given *state*
- to reach the goal, the state has to be changed to the desired state
- ATP can be used for finding the actions which can produce the change, but the application of the actions may be dependent on certain conditions
- the *resolution tree* can be transformed into a *decision tree* by introducing an algorithm for extracting information

Type D

Example

- if someone is younger than 5, then (s)he has to take medicine *a*

$$C_1 : \neg p(x) \vee r(x, a)$$

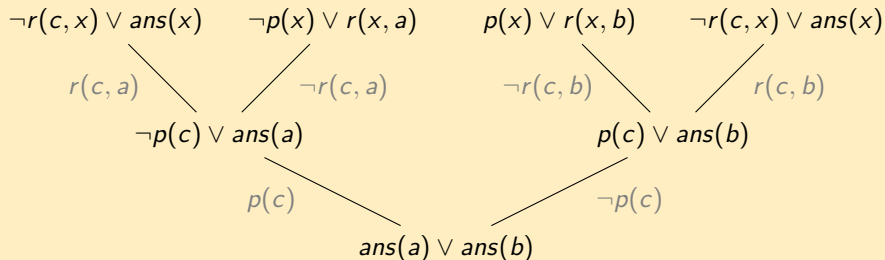
- if someone is not younger than 5, then (s)he has to take medicine *b*

$$C_1 : p(x) \vee r(x, b)$$

- which medicine should Carl take?

$$C_0 : \neg r(c, x) \vee ans(x)$$

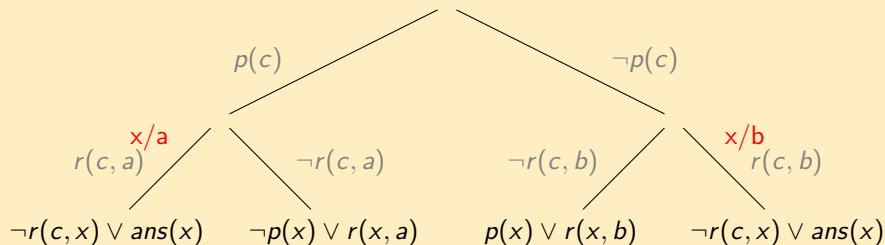
Example



- let $C\alpha \vee D\alpha$ be the resolvent of $L' \vee C$ and $\neg L'' \vee D$, with $\alpha = \text{MGU}(L', L'')$
- let e' be the edge from $L' \vee C$ to $C\alpha \vee D\alpha$
- let e'' be the edge from $\neg L'' \vee D$ to $C\alpha \vee D\alpha$
- then, e' is labelled with $\neg L'\alpha$ (note the \neg)
- and e'' is labelled with $L''\alpha$ (note that there is no \neg)

Type D

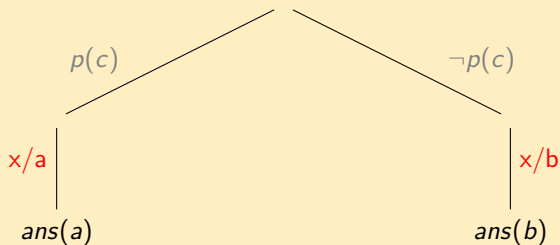
Example



- put the tree upside-down and remove clauses from non-leaf nodes

Type D

Example



- ignore paths leading to clauses without *ans*, and clean irrelevant parts

Conclusion

Completeness

- resolution is complete for answer extraction: if a question has an answer, then an *answer clause* can be deduced by resolution

Questions and answers

- let \mathcal{C} a set of clauses, representing *facts*
- let *find values for $x_1..x_k$ such that $p(x_1..x_k)$ holds* be the question
- the question has an answer iff $\mathcal{C} \vdash \exists x_1.. \exists x_k p(x_1..x_k)$
- the *query* Q will be $\neg p(x_1..x_k) \vee ans(x_1..x_k)$

Theorem

The question has an answer iff there exists a deduction of an answer clause starting from $\mathcal{C} \cup \{Q\}$

- *resolution not only tells if there is an answer, but also what this answer is*